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INFORMATION DISCLOSURE STATEMENT BY APPLICANT <i>(use as many sheets as necessary)</i>		Application Number	10/622,751
		Filing Date	07/18/2003
		First Named Inventor	Tarler
		Group Art Unit	2855
		Examiner Name	Alundra Ellington
Sheet	1	of	1
		Attorney Docket Number	CMD-006

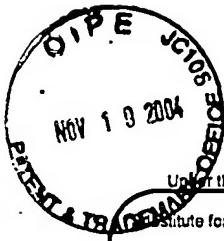
Examiner Signature	<u>Alandra Ellington</u>	Date Considered	3/28/05
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(Information Disclosure Statement—Section 2, FORM 1449A/PTO (PTO/SB/08A) [6-1] — page 5 of 8)



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INFORMATION DISCLOSURE
STATEMENT BY APPLICANT

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Sheet

1

of

1

Complete if Known

Application Number	10/622,751
Filing Date	07/18/2003
First Named Inventor	Tarter
Art Unit	2855
Examiner Name	Alandra Ellington
Attorney Docket Number	CMD-006

NON PATENT LITERATURE DOCUMENTS

Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
(ae)		DAISUKE YAMADA et al. Design of Artificial Finger Skin Having Ridges and Distributed Tactile Sensors, Proceedings of the 32nd ISR, 19-21 April 2001, pp. 1243-1248.	✓
G		DAISUKE YAMADA et al. Artificial Finger Skin Having Ridges and Distributed Tactile Sensors used for Grasp Force Control, Proceedings of the IROS 2001.	✓
		DAISUKE YAMADA et al. Artificial Finger Skin Having Ridges and Distributed Tactile Sensors used for Grasp Force Journal of Robotics and Mechatronics, Vol. 14, No.2, 2002.4, pp. 140-146.	✓
		STEPHEN A. MASCARO et al. Measurement of Finger Posture and Three-Axis Fingertip Touch Force Using Fingernail Sensors, Submitted to IEEE Transactions on Robotics and Automation, 2002.	✓
		TAKASHI MAENO et al. Analysis and Design of a Tactile Sensor Detecting Strain Distribution Inside an Elastic Finger, Jhttp://www.maeno.mech.keio.ac.jp/English/maeno_IROS98.pdf	✓
		STEPHEN A. MASCARO et al. Finger Posture and Shear Force Measurement using Fingernail Sensors: Initial Experimentation, Proceedings of the IEEE International Conference on Robotics and Automation, Vol. 2, pp. 1857-1862, 2001.	✓
		ROBERT D. HOWE et al. Dynamic Tactile Sensing: Perception of Fine Surface Features with Stress Rate Sensing, IEEE Transactions on Robotics and Automation, Vol. 9, No.2, April 1994	✓
		W. B. CARLSON et al. Flexi-Distortional Piezoelectric Sensor Results, http://design.alfred.edu/Piezoseignity/Plate Distort Sensors3.html, March 2003.	✓
↓		D. J. BEEBE et al. A Silicon Force Sensor for Robotics and Medicine, Sensors and Actuators A: Physical, Vol.50, Issues 1-2, August 1995, pp. 55-65.	✓
(ae)		J. L. NOVAK. Initial Design and Analysis of a Capacitive Sensor for Shear and Normal Force Measurement, IEEE, 1989, pp. 137-144.	✓

Examiner Signature	Alandra Ellington	Date Considered	3/28/05
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1 Applicant's unique citation designation number (optional). 2 Applicant is to place a check mark here if English language Translation is attached.

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